

Chapter 4

Mathematical Expectation

Probability & Statistics *for Engineers & Scientists*

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Section 4.1

Mean of a Random Variable

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Definition 4.1



Let X be a random variable with probability distribution $f(x)$. The **mean**, or **expected value**, of X is

$$\mu = E(X) = \sum_x x f(x)$$

if X is discrete, and

$$\mu = E(X) = \int_{-\infty}^{\infty} x f(x) dx$$

if X is continuous.

Theorem 4.1



Let X be a random variable with probability distribution $f(x)$. The expected value of the random variable $g(X)$ is

$$\mu_{g(X)} = E[g(X)] = \sum_x g(x)f(x)$$

if X is discrete, and

$$\mu_{g(X)} = E[g(X)] = \int_{-\infty}^{\infty} g(x)f(x) dx$$

if X is continuous.

Definition 4.2



Let X and Y be random variables with joint probability distribution $f(x, y)$. The mean, or expected value, of the random variable $g(X, Y)$ is

$$\mu_{g(X,Y)} = E[g(X, Y)] = \sum_x \sum_y g(x, y) f(x, y)$$

if X and Y are discrete, and

$$\mu_{g(X,Y)} = E[g(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f(x, y) dx dy$$

if X and Y are continuous.

Section 4.2

Variance and Covariance of Random Variables

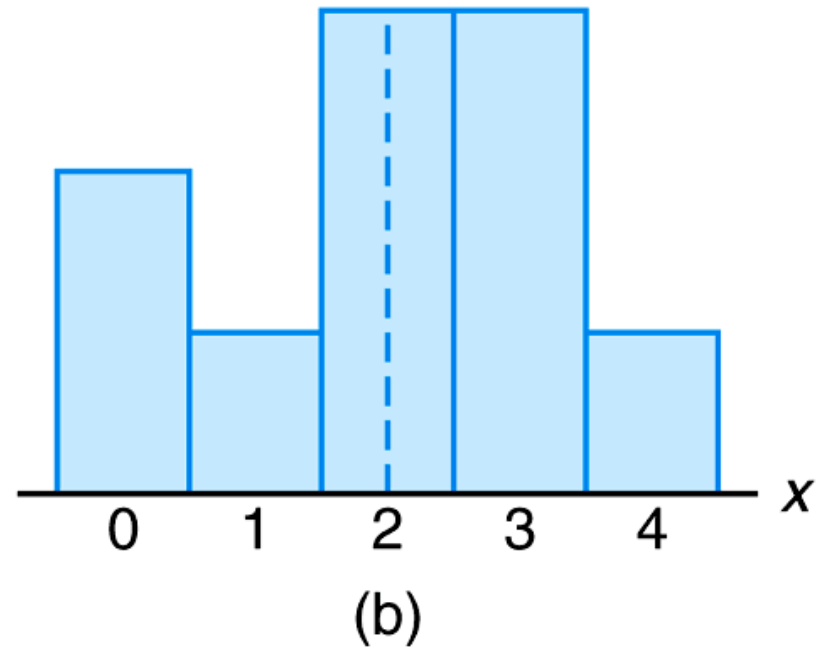
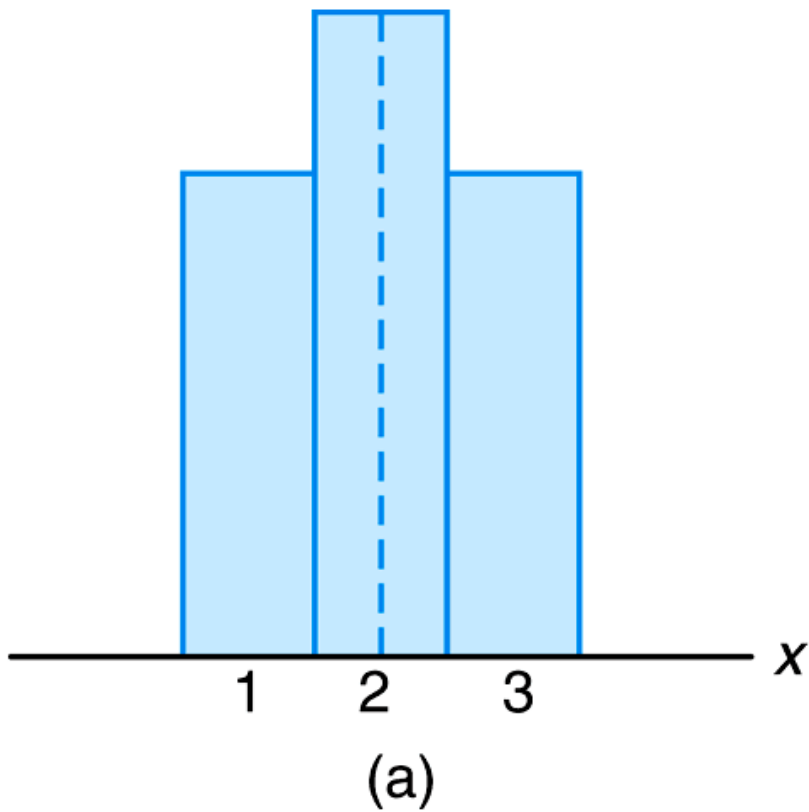
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Figure 4.1 Distributions with equal means and unequal dispersions



Definition 4.3



Let X be a random variable with probability distribution $f(x)$ and mean μ . The variance of X is

$$\sigma^2 = E[(X - \mu)^2] = \sum_x (x - \mu)^2 f(x), \quad \text{if } X \text{ is discrete, and}$$

$$\sigma^2 = E[(X - \mu)^2] = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx, \quad \text{if } X \text{ is continuous.}$$

The positive square root of the variance, σ , is called the **standard deviation** of X .

Theorem 4.2



The variance of a random variable X is

$$\sigma^2 = E(X^2) - \mu^2.$$

Theorem 4.3



Let X be a random variable with probability distribution $f(x)$. The variance of the random variable $g(X)$ is

$$\sigma_{g(X)}^2 = E\{[g(X) - \mu_{g(X)}]^2\} = \sum_x [g(x) - \mu_{g(X)}]^2 f(x)$$

if X is discrete, and

$$\sigma_{g(X)}^2 = E\{[g(X) - \mu_{g(X)}]^2\} = \int_{-\infty}^{\infty} [g(x) - \mu_{g(X)}]^2 f(x) dx$$

if X is continuous.

Definition 4.4



Let X and Y be random variables with joint probability distribution $f(x, y)$. The covariance of X and Y is

$$\sigma_{XY} = E[(X - \mu_X)(Y - \mu_Y)] = \sum_x \sum_y (x - \mu_X)(y - \mu_Y) f(x, y)$$

if X and Y are discrete, and

$$\sigma_{XY} = E[(X - \mu_X)(Y - \mu_Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y) f(x, y) dx dy$$

if X and Y are continuous.

Theorem 4.4



The covariance of two random variables X and Y with means μ_X and μ_Y , respectively, is given by

$$\sigma_{XY} = E(XY) - \mu_X\mu_Y.$$

Definition 4.5



Let X and Y be random variables with covariance σ_{XY} and standard deviations σ_X and σ_Y , respectively. The correlation coefficient of X and Y is

$$\rho_{XY} = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}.$$

Section 4.3

Means and Variances of Linear Combinations of Random Variables

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Theorem 4.5



If a and b are constants, then

$$E(aX + b) = aE(X) + b.$$

Corollary 4.1



Setting $a = 0$, we see that $E(b) = b$.

Corollary 4.2



Setting $b = 0$, we see that $E(aX) = aE(X)$.

Theorem 4.6



The expected value of the sum or difference of two or more functions of a random variable X is the sum or difference of the expected values of the functions. That is,

$$E[g(X) \pm h(X)] = E[g(X)] \pm E[h(X)].$$

Theorem 4.7



The expected value of the sum or difference of two or more functions of the random variables X and Y is the sum or difference of the expected values of the functions. That is,

$$E[g(X, Y) \pm h(X, Y)] = E[g(X, Y)] \pm E[h(X, Y)].$$

Corollary 4.3



Setting $g(X, Y) = g(X)$ and $h(X, Y) = h(Y)$, we see that

$$E[g(X) \pm h(Y)] = E[g(X)] \pm E[h(Y)].$$

Corollary 4.4



Setting $g(X, Y) = X$ and $h(X, Y) = Y$, we see that

$$E[X \pm Y] = E[X] \pm E[Y].$$

Theorem 4.8



Let X and Y be two independent random variables. Then

$$E(XY) = E(X)E(Y).$$

Corollary 4.5



Let X and Y be two independent random variables. Then $\sigma_{XY} = 0$.

Theorem 4.9



If X and Y are random variables with joint probability distribution $f(x, y)$ and a , b , and c are constants, then

$$\sigma_{aX+bY+c}^2 = a^2\sigma_X^2 + b^2\sigma_Y^2 + 2ab\sigma_{XY}.$$

Corollary 4.6



Setting $b = 0$, we see that

$$\sigma_{aX+c}^2 = a^2 \sigma_X^2 = a^2 \sigma^2.$$

Corollary 4.7



Setting $a = 1$ and $b = 0$, we see that

$$\sigma_{X+c}^2 = \sigma_x^2 = \sigma^2.$$

Corollary 4.8



Setting $b = 0$ and $c = 0$, we see that

$$\sigma_{aX}^2 = a^2 \sigma_X^2 = a^2 \sigma^2.$$

Corollary 4.9



If X and Y are independent random variables, then

$$\sigma_{aX+bY}^2 = a^2\sigma_X^2 + b^2\sigma_Y^2.$$

Corollary 4.10



If X and Y are independent random variables, then

$$\sigma_{aX-bY}^2 = a^2\sigma_X^2 + b^2\sigma_Y^2.$$

Corollary 4.11



If X_1, X_2, \dots, X_n are independent random variables, then

$$\sigma_{a_1 X_1 + a_2 X_2 + \dots + a_n X_n}^2 = a_1^2 \sigma_{X_1}^2 + a_2^2 \sigma_{X_2}^2 + \dots + a_n^2 \sigma_{X_n}^2.$$